

# Maximasekvenser

Detta dokument innehåller bokens Maximasekvenser så att man enkelt kan kopiera dem till Maxima.

**2.1** `2.56; 1/2; 15/25; %pi; sqrt(2); sqrt(4);`

**2.2** `1/2, numer; %pi, numer; sqrt(2), numer;`

**2.3** `(3/5)/2; 3/(5/2); 3/5/2;`

**2.4** `126/150; 9/10-3/14-13/21; (5/12+2/3)/(17/10-3);`

**2.5** `2^(1/2); 2^(1/2), numer; 2^0.5; 4^(1/2); 4^0.5;`

**3.1** `expr1:(s+t)^2-(s-t)^2; expand(expr1);`

**3.2** `expr2:(a/2-(8-a)/(a-2))/(a-4); factor(expr2);`

**3.3** `expr3:(1/a+1/b)/(1/a-1/b); factor(expr3);`

**3.4** `expr4:(a*b-2*c*d)/(2*b*d); expand(expr4);`

**3.5** `ekv:10+5*x-2*x^2=20*x-5*x^2-8$ solve(ekv);`

**3.6** `solve(x^2+a*x+9=0, x);`

**3.7** `solve(x^2+10=0);`

**3.8** `expand(y*(y-1)*(y+1));`

- 3.9** `pol:(s^4+2*s^2)*(-s^2-3)*(3/4+(1/2)*s); expand(pol);`
- 3.10** `divide(x^3+x^2+x+1, x-1);`
- 3.11** `quotient(x^3+x^2+x+1, x-1),`
- 3.12** `remainder(x^3+x^2+x+1, x-1);`
- 3.13** `divide(x^3+x^2+x+1, x+1);`
- 3.14** `divide(x^5+x^2+1, x^2-2*x+1);`
- 3.15** `f1:(x^2-1)/(x^2-x); factor(f1); ratsimp(f1);`
- 3.16** `f2:((2*x+3)^2-(x-3)^2)/(4-(x+2)^2); factor(f2);  
ratsimp(f2);`
- 3.17** `ekv:(x^2+9)*(x^2-9)=9*x^2-x^4; solve(ekv);`
- 3.18** `expr:x^5+200x^2+100x-1500; find_root(expr, -5,5);`
- 3.19** `expr2:(x+6)^(1/3)-x; solve(expr2=0); find_root(expr2,0,5);`
- 3.20** `load(solve_rat_ineq)$  
solve_rat_ineq(x+4>60/x);`
- 4.1** `sum(k,k,0,10);`
- 4.2** `sum(k,k,1,n);  
%, simpsum;`
- 4.3** `sum(4+k*3, k,0,p), simpsum;`
- 4.4** `ratsimp(%); factor(%);`
- 4.5** `sum((i/n)^2, i,1,n), simpsum;`
- 4.6** `sum((-1)^(i+1)*(2/(3^i)), i,0,n)-sum((-1)^(i+1)*5^i, i,0,n),  
simpsum;`

- 4.7** `expand((1+x)^3); expand((2-t)^4); expand((3*a+2*b)^3);`
- 5.1** `load(implicit_plot)$  
implicit_plot(x^2+y^2=16, [x,-5,5], [y,-5,5], same_xy)$`
- 5.2** `load(implicit_plot)$  
implicit_plot([9*x^2-4*y^2=9, 2*y+3*x=0, 2*y-3*x=0],  
[x,-4,4], [y,-4,4], same_xy)$`
- 6.1** `sin(%pi/2); cos(45*%pi/180); cos(1);`
- 6.2** `sin(%pi/2), numer; cos(45*%pi/180), numer; cos(1), numer;`
- 6.3** `trigexpand(cos(2*v)); trigsimp((sin(v))^2+(cos(v))^2);  
trigexpand(sin(u+v)); trigexpand(sin(3*v));  
trigreduce(cos(u)*cos(v));  
trigreduce((sin(x))^3);`
- 6.4** `acos(0); asin(1); acos(0.5); asin(-1/2);`
- 7.1** `log(1); log(%e); log(%e^2); log(10);`
- 7.2** `log(10), numer; log(100), numer; log(10.0);`
- 7.3** `log(2)/log(10), numer; log(100)/log(10), numer;`
- 7.4** `log(5)/3, numer;`
- 8.1** `f(x):=x^2; f(-1); f(2); plot2d(f(x), [x,-3,3])$`
- 8.2** `plot2d([x^2, 9-x^2], [x,-3,3], same_xy)$  
g2(x):=if x<-1 then x+2 else if x<1 then 1 else -x+2$  
plot2d(g2(x), [x,-3,3], [y,-1,1.5])$`
- 8.3** `plot2d([x/2+5, 2*x-10, x], [x,-20,20], same_xy)$`
- 8.4** `f(x):=1/x$  
plot2d(f(x), [x,-5,5])$`
- 8.5** `plot2d(f(x), [x,-5,5], [y,-5,5])$`

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8.6 load(implicit_plot)$  
    implicit_plot(x^2+y^3=5, [x,-5,5], [y,-5,5])$  
  
9.1 limit((x^2-4)/(4*(x-2)), x, 2);  
    limit(sqrt(1+3/x), x, minf);  
    limit(cos(x)*1/x, x, inf);  
  
10.1 f(x):=x^2$ g(x):=2*x-1$ plot2d([f(x), g(x)], [x,0.5,1.5])$  
    plot2d([f(x), g(x)], [x,0.99,1.01])$  
  
10.2 f(x):=x^3+sin(x); 'diff(f(x), x)=diff(f(x), x);  
  
10.3 f(x):=log(x+sqrt(x^2+1))$ diff(f(x), x); factorfacsum(%);  
  
10.4 g(x):=(x+2)/(1+(3*x+2)/(x+1)); diff(g(x), x)$ factor(%);  
  
10.5 diff(3*y(x)^2+x^3=11, x); solve(%, diff(y(x), x));  
  
10.6 plot2d([parametric, t*cos(t), t*sin(t)], [t,0,10])$  
  
10.6 f(x):=abs(x-round(x))$  
    bl(x):=sum(1/2^k*f(2^k*x), k,0,12)$  
    plot2d(bl(x), [x,0,1])$  
  
11.1 plot2d((x^3-3*x), [x,-3,3], [y,-10,10], same_xy);  
  
11.2 plot2d(1/2*x^2/(x-1), [x,-5,5], [y,-10,10], same_xy);  
  
11.3 plot2d(abs(x)*(x+2), [x,-2,1], same_xy);  
  
11.4 diff((x^2+1)/x+atan(x), x);  
  
11.5 factor(%);  
  
11.6 solve([x^4+x^2-1=0], [x]);  
  
12.1 taylor(%e^x, x, 0, 5); taylor((1+x)^(1/4), x, 0, 5);  
  
12.2 taylor(log(1+x), x, 0, 10);
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- 12.3**  $f(x) := x - x^2/2 + x^3/3 - x^4/4 + x^5/5 - x^6/6 + x^7/7 - x^8/8 + x^9/9 - x^{10}/10$   
`f(0.5), numer;`
- 12.4** `taylor(sin(x), x, %pi/2, 8);`
- 13.1** `'integrate(1/x^3, x) = integrate(1/x^3, x);`  
`'integrate(sqrt(x), x) = integrate(sqrt(x), x);`  
`'integrate(3*e^x - 2*cos(x), x) =`  
`integrate(3*e^x - 2*cos(x), x);`  
`'integrate(1/(1+4*x^2), x) = integrate(1/(1+4*x^2), x);`  
`'integrate(1/sqrt(1-9*x^2), x) =`  
`integrate(1/sqrt(1-9*x^2), x);`
- 13.2**  $f(x) := (x+5)/(x^2+x-2);$   
`partfrac(f(x), x);`
- 13.3**  $f(x) := (x-1)/(x*(x^2+1));$   
`partfrac(f(x), x);`
- 13.4**  $f(x) := x^3/(x^2+2*x+2);$   
`partfrac(f(x), x);`
- 13.5**  $f(x) := (x^3-2x+1)/(x^3*(x^2+1));$   
`partfrac(f(x), x);`
- 13.6** `'integrate((sin(x))^4, x) = trigsimp(integrate((sin(x))^4, x));`
- 13.7** `'integrate(1/sin(x), x) = integrate(1/sin(x), x), logabs;`
- 13.8** `'integrate(sqrt(x^2+1), x) = integrate(sqrt(x^2+1), x);`
- 13.9** `'integrate(1/sqrt(x^2+1), x) = integrate(1/sqrt(x^2+1), x);`
- 13.10** `'integrate(%e^(3*x)*sin(2*x), x) =`  
`integrate(%e^(3*x)*sin(2*x), x);`
- 13.11** `'integrate(%e^x*sin(2*x)*cos(3*x), x) =`  
`trigsimp(integrate(%e^x*sin(2*x)*cos(3*x), x));`
- 14.1**  $f(x) := x^2;$   
`Riemannsumma(n) := sum(f(k/n)*1/n, k, 1, n);`  
`Riemannsumma(n), simpsum;`

- 14.2** `Riemannsumma(10);`  
    `%,numer;`  
    `Riemannsumma(100),numer;`  
    `Riemannsumma(1000),numer;`  
    `limit(Riemannsumma(n),n,inf),simpsum;`
- 14.3** `'integrate(x^2,x,0,2)=integrate(x^2,x,0,2);`
- 14.4** `'integrate(1/(x+sqrt(x)),x,1,4)=`  
    `integrate(1/(x+sqrt(x)),x,1,4);`
- 14.5** `integrate((x-1)/(x*(x^2+1)),x,1,inf);`
- 16.1** `ekv:'diff(y,t,1)=-k*y;`  
    `sol:ode2(ekv,y,t);`  
    `ic1(%,t=0,y=y0);`
- 16.2** `load(plotdf)$`  
    `plotdf(2*x*(y^2-y),[xcenter,0],[xradius,2],`  
        `[ycenter,0],[yradius,2])$`
- 16.3** `plotdf(2*x*(y^2-y),[xcenter,0],[xradius,2],`  
    `[ycenter,0],[yradius,2],[trajectory_at,0,0.5])$`
- 16.4** `assume(w>0);`  
    `ekv:'diff(y,t,2)+w^2*y=(F/m)*cos(b*t);`  
    `ode2(ekv,y,t);`
- 16.5** `assume(w>0);`  
    `ekv:'diff(y,t,2)+w^2*y=(F/m)*cos(w*t);`  
    `ode2(ekv,y,t);`
- 16.6** `assume(M>y, y>0);`  
    `ekv:'diff(y,t,1)=k*y*(M-y);`  
    `ode2(ekv,y,t),logabs;`
- 16.7** `solve(y/(M-y)=(a/(M-a))*exp(k*M*t),y);`